

## Data structures n' containers in C++

### ARRAY: #include <vector>

push_back( ) pop_back( ) operator [ ]	$O(1)$	begin( ) end( ) insert( ) erase( )	$O(n)$	size() empty()
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### LIST: #include <list>

push_front( ) push_back( ) pop_back( ) pop_front( )	$O(1)$	begin( ) end( ) insert( ) erase( )	$O(n)$	size() empty()
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### STACK: #include <stack>

push( ) pop( ) top( )	$O(1)$			size() empty()
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### QUEUE: #include <queue>

push( ) pop( ) front( ) back( )	$O(1)$			size() empty()
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### MAX BINARY HEAP: #include <priority\_queue>

push( ) pop( )	$O(\log n)$	top( )	$O(1)$	size() empty()
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### BINARY SEARCH TREE: #include <set> or <map>

insert( ) erase( ) operator [ ] (map only)	$O(\log n)$	begin( ) end( ) find( ) count( )	$O(\log n)$ <i>return iterator or set::end</i> <i>return 0 or 1</i>	size() empty()
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Nota: if you want to insert several times the same value prefer to use <multiset> or <multimap> but operator [ ] will be not available anymore.

### HASH TABLE: #include <unordered\_set> or <unordered\_map>

insert( ) erase( ) operator [ ] (unordered_map only)	$O(1)$	begin( ) end( ) find( ) count( ) reserve( )	$O(1)$ <i>return iterator or set::end</i> <i>return 0 or 1</i> <i>set the number of buckets</i>	size() empty()
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Nota: hash\_table is a very efficient data structure but elements can not be ordered.

For the following data structures there is no base container implemented in C++ so you have to do by hand.

**MIN BINARY HEAP:** the package `<algorithm>` contains a function `make_heap()` to make a binary heap and by default this is a max binary heap.

```
std::vector<int> minHeap;
std::make_heap(minHeap.begin(), minHeap.end(), std::greater<int>());
// to add a value
minHeap.push_back(x);
push_heap(minHeap.begin(), minHeap.end(), std::greater<int>());
// to remove
pop_heap(minHeap.begin(), minHeap.end(), std::greater<int>());
minHeap.pop_back();
```

**BINARY TREE:** a simple binary tree is not very useful because you often need some properties (ordered, max value at root) which force you to use a `<set>` or `<map>` or `<priority_queue>`. If however you still want to implement one the easiest way is maybe to use a simple `<vector>` (like binary heaps) and to move through the tree using  $i * 2$  to get the left child and  $i * 2 + 1$  to get the right child. To insert an element you can perform a `push_back()` so your tree will be balanced. If you don't want this behavior we can use a struct node with pointers and implement a function to insert and delete an element:

```
class Node
{
    int key_value;
    node *left;
    node *right;
};
```

**GRAPH/N-ARIES TREE:** are nodes identified using index from 0 to N?

- YES => the node index (vertex) will match the vector index

```
vector<vector<int> > > graph;
```

or

```
vector<vector<pair<int, int> > > graph; //edges have weight
```

- NO => you have to create dedicated classes

```
class Edge;
class Vertex
{
    int id;
    vector<Edge*> ptr_edges;
}
class Edge
{
    Vertex *from;
    Vertex *to;
    int cost;
}
class Graph
{
    vector<Vertex> vertices;
}
```